## Event Based Markovian Simulation

The $\psi-3$ software

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## Outline

(1) Generation of Samples of Markov Chains

2 How to install $\Psi-3$

3 Simple trajectory

4 Simple trajectory of a network
(5) Scheduling

## Events and Poisson Systems

## $M / M / 1$ capacity $C=2$ <br> 

Queue
States


## Events and Poisson Systems



## Events and Poisson Systems



## Events and Poisson Systems



## Events and Poisson Systems



## Events and Poisson Systems



## Events and Poisson Systems



## Events and Poisson Systems


$\Rightarrow$ monotone events

## Event Modelling

Multidimensional state space : $\mathcal{X}=\mathcal{X}_{1} \times \cdots \times \mathcal{X}_{K}$ with $\mathcal{X}_{i}=\left\{0, \cdots, C_{i}\right\}$. Event $e$ :
$\sim$ transition function $\Phi(., e)$; (skip rule)
$\sim$ Poisson process $\lambda_{e}$


## Event modelling : Uniformization

$$
\Lambda=\sum_{e} \lambda_{e} \text { and } \mathbb{P}(\text { event } e)=\frac{\lambda_{e}}{\Lambda}
$$

Trajectory : $\left\{e_{n}\right\}_{n \in \mathbb{Z}}$ i.i.d. sequence.
$\Rightarrow$ Homogeneous Discrete Time Markov Chain [Bremaud 99]

$$
X_{n+1}=\Phi\left(X_{n}, e_{n+1}\right)
$$

Generation among a small finite space $\mathcal{E}: \mathcal{O}(1)$

## $\psi$ software




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## Software architecture

## Aim of the software

- finite capacity queueing network simulator
- rare events estimation (rejection, blocking,...)
- statistical guarantees (independence of samples)
$\Rightarrow$ Simulation kernel
- open source (C, GPL licence)
- extensible library of events
- multiplatforms (linux (debian), mac OSX,...)


## Workflow

| Samples |  |
| :---: | :---: |
| Single trajectory |  |
| Independent trajectories | \|"IIII ||" |
| Steady-state independent |  |
| Sample of rewards Coupling time |  |

## Workflow

> Model libraries $\begin{aligned} & \text { servercs, capacitics } \\ & \text { Event description }\end{aligned}$
> Rate
> $\begin{aligned} & \text { Activation condition } \\ & \text { Action of the event }\end{aligned}$

| Simulation kernels |
| :--- |
| Forward sampling |
| trajectories |
| Backwampling |
| $\quad$ Monotone |
| Envelopes |
| Envelopes and split |



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## Workflow



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## Workflow



## Workflow



## Workflow



## Modeling

## Syntax

Queues:

```
- id:
[parameter_1]:
[id_value]
[parameter_2_value]
```


## Example

Queues:

- id:
queue1
min:
0
$\max :$
50
- id:
queue2
min:
0
max:
80


## Modeling

## Short list

ext_arrival_reject One client comes from outside to the listed queues with priorities (the list order). The client is rejected if not possible.
ext_departurer One client lives the specified queue.
routing_n_queues_reject Select a client from the listed queues and route to another queue. Client is rejected if routing is not possible.
routage_nfile_bloc Select a client from the listed queues and route to another queue. Client stays on the origin queue if routing is not possible.
JSQ_rejet Select a client from the listed queues and route to another queue with the least clients. Client is rejected if routing is not possible.

## Modeling

## Syntax

Events:

```
- id:
[parameter_1]: [parameter_2_value]
```


## Example

```
Events:
    - id:
    type:
    rate:
    from:
    to:
- id:
    type:
    rate:
    from:
    to:
    evt1
    Default$ext_arrival_reject
    1.6
    [outside]
    [queue1, drop]
    evt2
    Default$ext_departure
    2.0
    [queue1]
    [drop]
```


## Simulation

## Single trajectory sampling (Monte Carlo)

- Simple forward
- Simple forward parallel


## Perfect sampling (Propp \& Wilson) and extensions

- Bakward Monotone
- Bakward Envelope
- Bakward Envelope Splitting


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## Installation

- Unix-like operating system: GNU/Linux, MacOSX
- C/C++ compiler
- GCC >= 4.4 (for OpenMP 3.0 support)
- CMake > 3.0


## Installation

PSI3 will be installed in /usr/local.

```
In the source directory:
cmake .
make
sudo make install
```


## Installation

Installation destination can be changed through CMAKE_INSTALL_PREFIX. For instance, installing in \$HOME/psi3:

## In the source directory:

```
DESTDIR="$HOME/psi3"
cmake -D CMAKE_INSTALL_PREFIX="$DESTDIR" .
make
sudo make install
```

Then, you can update your Path to run PSI3:

## In shell:

export PATH="\$DESTDIR/bin:\$PATH"

## Installation

## Notes for mac user

- Although PSI3 can compile and works with clang, our advise is to use gcc.
- If you don't have gcc, you can install it through homebrew (http://brew.sh/)
- If notice CMAKE still use clang. Check the value of CMAKE_C_COMP ILER. CCMAKE offers a graphical front-end that is often a good choice to get a good overview of variables used by CMAKE.


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## Example

## Overview



## 1 Queue

```
- id:
    queue1
min:
0
max:
5 0
```


## Example

## Overview



## 2 Events

- ext_arrival_reject
- ext_departure


## Example

## Overview



## Event 1

- id:
type:
rate:
from:
to:
evt1
Default\$ext_arrival_reject
1.6
[outside]
[queue1, drop]


## Example

## Overview



## Event 2

- id:
type:
rate:
from:
to:
evt2
Default\$ext_departure
2.0
[queue1]
[drop]


## Example

## model.yaml

Queues:

- id:
min:
max:
Events:
- id:
type:
rate:
from:
to:
- id:
type:
rate:
from:
to:
queue1
0
50
evt1
Default\$ext_arrival_reject
1.6
[outside]
[queue1, drop]
evt2
Default\$ext_departure
2.0
[queue1]
[drop]


## Example

## Simpleforward

To generate a trajectory of this model.

```
simpleforward.yaml
Method: simpleforward
# Sample will have one million states
TrajectoryLength: 1000000
# Initial states of queues.
# "~" means to let PSI3 choose it randomly.
InitialState :
```


## Example

```
param.yaml
# Random generator seed. "~" for random seed
Seed:
# Configuration of model
PrintModel: Yes
# Parameters of simulation
PrintParam: Yes
# Total time of the simulation from begin to end
PrintSimulationTime: Yes
```


## Example

```
Execution
> psi3_unix -m simple-queue.yaml -p param.yaml
-k simpleforward.yaml
Begin user files compilation...
OK
Begin simulation...
Number total of transition calls: 1000000
# Total simulation time : 297.071000 milli-seconds
End of simulation
```


## Example

```
output.txt (troncated)
# PSI3 INFO:
# version: 1.3.0
# build type: DEBUG
# C compiler: GNU
# compiler options: -Werror -Wall -rdynamic
# General Param:
# seed: 7
# Method:
# TrajectoryLength: 1000
# InitialState: 24
```


## Example

```
output.txt (truncated)
# Output data:
O Na 24
1 1 23
2 1 22
3 0 23
4 0 24
5 1 23
999998 1 0
999999 0 1
# Number total of transitions calls: 999999
# Total simulation time: 233.257000 milli-seconds
```


## Example

With a simple script R available on this page: http://psi.gforge.inria.fr/dokuwiki/doku.php?id=psi3:examples

## R output



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## Overview



## 2 Queues

Queues:

- id:
min:
queue1
max:
0
50
- id:
queue2
min:
0
max:
50


## Example

## Overview



## 2 Events

- ext_arrival_reject
- routing_n_queues_reject
- ext_departure


## Example

## Overview



## Event 1

```
- id:
type:
rate:
from:
    to:
```

evt1
Default\$ext_arrival_reject
1.6
[outside]
[queue1, drop]

## Example

## Overview



## Event 2

- id:
type:
rate:
from:
to:
evt2
Default\$routing_n_queues_reject
1.8
[queue1]
[queue2]


## Example

## Overview



## Event 3

```
- id:
type:
rate:
from:
to:
```

evt2
Default\$ext_departure
2.0
[queue1]
[drop]

## Example

## BackwardMonotone

To sample 1000 steady states of the system..

```
method.yaml
# Simulation algorithm
Method: backwardmonotone
# Sample number
SampleNumber: 1000
# Number of Antithetic variable
Antithetic:
    1
# Doubling period (Yes or No)
Doubling: Yes
# Size of maximal trajectory
TrajectoryMax: 3000000
```


## Example

```
param.yaml
# Random generator seed. "~" for random seed
Seed:
7
# Configuration of model
PrintModel: Yes
# Parameters of simulation
PrintParam: Yes
# Total time of the simulation from begin to end
PrintSimulationTime: Yes
```


## Example

## Execution

> psi3_unix -m simple-queue.yaml -p param.yaml
-k simpleforward.yaml

Begin user files compilation...
OK
Begin simulation...
InitMemoryLength: automatic default value (1000)
\# Total simulation time: 287.465000 milli-seconds
End of simulation

## Example

```
output.txt (truncated)
# PSI3 INFO:
# version: 1.3.0
# build type:
# C compiler: GNU
# compiler options: -Werror -Wall -rdynamic
# General Param:
# seed: 3
# Method:
# SampleNumber: 1000
# TrajectoryMax: 3000000
# Antithetic: 1
# Doubling: 1
# InitMemoryLength: 1000
```


## Example

```
output.txt (truncated)
# Output data:
0 14 7 - 10
1 2 8 - 11
2 2 3 - 11
3 3 4 - 11
996 0 3 - 10
997 3 1 - 10
998 6 0 - 10
999 15 1 - 10
# Total simulation time: 287.465000 milli-seconds
```


## Example

With a simple script $R$ available on this page:
http://psi.gforge.inria.fr/dokuwiki/doku.php?id=psi3:examples

## R output



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## Example

## Overview



## Two kind of event

- JSQ_rejet

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- ext denartıire


## Example

## model.yaml (1)

Queues:

- id:
queue0
min:
0
max:
10
- id:
min:
queue1
max:
0
- id:
min:
max:
10
max: 10


## Events:

- id:
type:
rate:
from:
evt1
Default\$JSQ_rejet
5.0
to:
[outside]
[queue0, queue1, queue2, drop]


## Example

## model.yaml (2)

- id:
type:
rate:
from:
to:
- id:
type:
rate:
from:
to:
- id:
type:
rate:
from:
to:

```
evt2
Default$ext_departure
2.0
    [queue0]
    [drop]
    evt3
    Default$ext_departure
    2.0
    [queue1]
    [drop]
    evt4
    Default$ext_departure
    2.0
    [queue2]
    [drop]
```


## Example

## BackwardMonotone

- To sample 1000 steady states of the system
- User defined output function to print max and min of queues

```
method.yaml
# Simulation algorithm
Method: backwardmonotone
# Sample number
SampleNumber: }100
# Doubling period (Yes or No)
Doubling: Yes
# Size of maximal trajectory
TrajectoryMax: 3000000
MyLib: [lib/outputfct]
OutputFct: MyLib$output_minmax
```


## Example

```
void output_minmax (FILE * f, int **state,
        int sample, int *log2stop_time)
{
    int i, n,max = 0, min = 0;
    fprintf (f, "%d_\t", sample);
    for (n = 0; n < nb_AV; n++) {
        min = state[n][0];
        max = state[n][0];
        for (i = 1; i < nb_queues; i++) {
        max = max2 (max, state[n][i]);
        min = min2 (min, state[n][i]);
        }
        fprintf (f, "%d\t%d\n", min, max);
    }
}
```


## Example

```
param.yaml
# Random generator seed. "~" for random seed
Seed:
# Configuration of model
PrintModel: Yes
# Parameters of simulation
PrintParam: Yes
# Total time of the simulation from begin to end
PrintSimulationTime: Yes
```


## Example

## Execution

> psi3_unix -m simple-queue.yaml -p param.yaml
-k simpleforward.yaml

Begin user files compilation...
OK
Begin simulation...
InitMemoryLength: automatic default value (1000)
\# Total simulation time: 73.659000 milli-seconds
End of simulation

## Example

```
output.txt (truncated)
# Output data:
0 2 3
1 3 4
2 1 2
3 2 3
4 1 2
5 2 4
995 2 2
996 3 4
997 0 0
998 1 3
999 0 2
# Total simulation time: 73.659000 milli-seconds
```


## Example

## With a simple script R

## R output

Histogram of MaxStates


